In the Specification:

Please replace original paragraph **[0022]** with the following amended paragraph **[0022]:**

[0022] The relative position of the conveyor arrangement 34 to the take-up device 36 could be invariable, however as a rule, it is variable due to the support in bearings of the conveyor arrangement 34 on lever arms. The aforementioned lever arms on both sides are spring loaded in order to force the conveyor arrangement 34 against the crop. The position of the hold-down device 38 can be repositioned between the operating position, shown in FIG. 1 in solid lines, in which the hold-down device 38 interacts with the take-up device 36, and a non-operating position in which the hold-down device is shown in dashed lines indicated by number call-out 38'. For this purpose, a hydraulic cylinder 42 is used (which could also be replaced by an electric motor), that is arranged to rotate the hold-down device 38 about a horizontal axis 43 extending transverse to the direction of operation of the forage harvester 10. The non-operating position of the hold-down device 38 has been shown to be useful during reverse operation, in which the supply rolls 30, the conveyor arrangement 34, and the take-up device 36 (optionally also the chopper drum 22) are operated in a direction of rotation opposite to the normal harvesting operation, in order to be able to eject jammed material. The reverse operation is performed by the reversible hydraulic motor 126 ~~132~~ at the length-of-cut gearbox 124. Even when a metal detector, not shown, arranged within one of the supply rolls 30, responds and turns off the drive of the supply rolls 30, a reverse operation is appropriate.